

1. Using the expressions given, one finds directly:

$$\begin{aligned} \mathbf{E}' \cdot \mathbf{B}' &= E'_x B'_x + E'_y B'_y + E'_z B'_z \\ &= E_x B_x + (\cosh \zeta E_y - \sinh \zeta c B_z)(\cosh \zeta B_y + \sinh \zeta E_z/c) \\ &\quad + (\cosh \zeta E_z + \sinh \zeta c B_y)(\cosh \zeta B_z - \sinh \zeta E_y/c) \\ &= E_x B_x + E_y B_y + E_z B_z \\ &= \mathbf{E} \cdot \mathbf{B}, \end{aligned}$$

with the cross-terms cancelling and the others combining using  $\cosh^2 - \sinh^2 = 1$ . Similarly:

$$\begin{aligned} \mathbf{E}'^2 - c^2 \mathbf{B}'^2 &= E_x^2 + (\cosh \zeta E_y - \sinh \zeta c B_z)^2 + (\cosh \zeta E_z + \sinh \zeta c B_y)^2 \\ &\quad - c^2 B_x^2 - c^2 (\cosh \zeta B_y + \sinh \zeta E_z/c)^2 - c^2 (\cosh \zeta B_z - \sinh \zeta E_y/c)^2 \\ &= E_x^2 + E_y^2 + E_z^2 - c^2 B_x^2 - c^2 B_y^2 - c^2 B_z^2 \\ &= \mathbf{E}^2 - c^2 \mathbf{B}^2. \end{aligned}$$

2.

- (a) Writing  $I_1$  for  $\mathbf{E} \cdot \mathbf{B}$  and  $I_2$  for  $\mathbf{E}^2 - c^2 \mathbf{B}^2$ , one finds that if  $\mathbf{E}$  and  $\mathbf{B}$  are parallel,  $c^2 B^4 + I_2 B^2 - I_1^2 = 0$ . Since  $I_2^2 + 4I_1^2 c^2$  is clearly never negative, this gives two real solutions for  $B^2$ , and unless  $I_1 = 0$ , one and only one of these is positive, namely  $B^2 = (\sqrt{I_2^2 + 4I_1^2 c^2} - I_2)/2c^2$ . The existence of this solution confirms that there is no obstacle to finding a frame in which  $\mathbf{E}$  and  $\mathbf{B}$  are parallel, unless  $I_1 = 0$  in which case  $\mathbf{E}$  and  $\mathbf{B}$  would be perpendicular in *every* frame; and in that case the only way that they could also be parallel would be if one or the other vanishes— and that situation is dealt with below.
- (b) For there to exist a frame in which  $\mathbf{B} = 0$  it is clear that we require  $I_1 = 0$  and  $I_2 \geq 0$ . If in fact  $I_2 = 0$  it would follow that  $\mathbf{E}$  also vanishes, and we would have  $\mathbf{E} = \mathbf{B} = 0$  in every frame.
- (c) Likewise for there to exist a frame in which  $\mathbf{E} = 0$ , excluding the case when  $\mathbf{E} = \mathbf{B} = 0$  in every frame it is necessary and sufficient that  $I_1 = 0$  and  $I_2 < 0$ .
- (d) In this case  $I_1 = 0 = I_2$  in every frame but  $\mathbf{B}$  and  $\mathbf{E}$  are non-zero in every frame.

3. We know that

$$P^\mu = (E/c, \mathbf{p})$$

is a 4-vector and that  $d\tau$  is a scalar, where

$$c^2 d\tau^2 = c^2 dt^2 - dx^2 - dy^2 - dz^2,$$

so that

$$\frac{d\tau}{dt} = \left(1 - \frac{\mathbf{v}^2}{c^2}\right)^{\frac{1}{2}} = \frac{1}{\gamma}.$$

It follows that  $\frac{dP^\mu}{d\tau}$  is a 4-vector, *i.e.*

$$\begin{aligned} \frac{dP^\mu}{dt} \frac{dt}{d\tau} &= \gamma \frac{dP^\mu}{dt} \\ &= \gamma \left( \frac{dP^0}{dt}, \mathbf{f} \right), \end{aligned}$$

and since  $cP^0 = E$  and its time-derivative is just the rate at which the force  $\mathbf{f}$  does work, *viz.*  $c \frac{dP^0}{dt} = \mathbf{v} \cdot \mathbf{f}$ , we have obtained the desired result. We have also identified  $F^0$  as the proper time derivative of  $P^0$ , *i.e.* up to a factor of  $c$  of the energy.